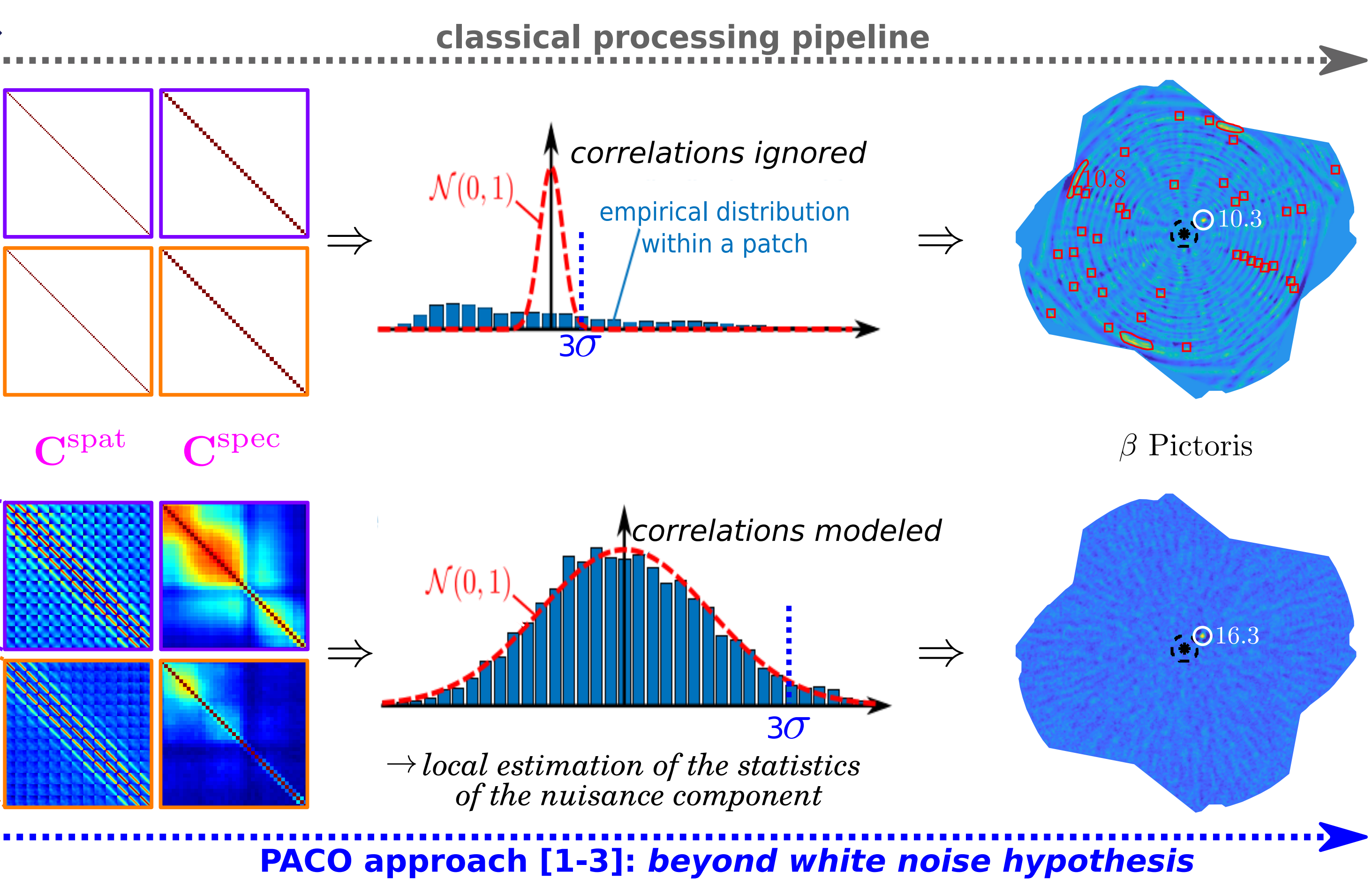
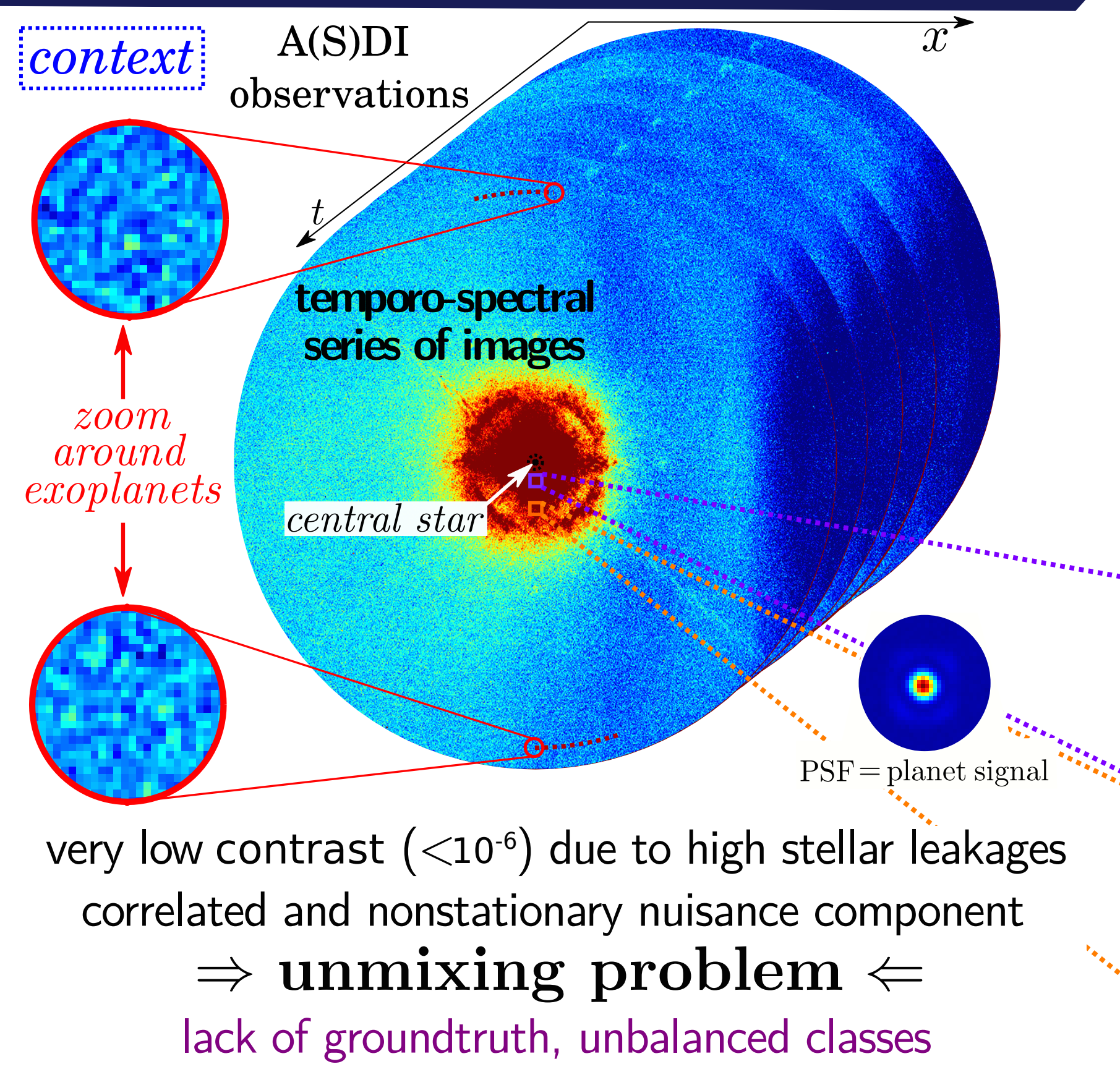




Olivier Flasseur<sup>a,b</sup>, Théo Bodrito<sup>b</sup>, Samuel Thé<sup>c</sup>, Julien Mairal<sup>b</sup>, Jean Ponce<sup>b</sup>, Anne-Marie Lagrange<sup>a,d</sup>, Maud Langlois<sup>c</sup>, Eric Thiébaud<sup>c</sup>, Loïc Denis<sup>e</sup>

### 1. Statistical modeling of the nuisance



**statistical model** → GSM model:  

$$f_{n,t,\lambda} = m_{n,\lambda} + \kappa_{n,t} \mathbf{u}_{n,t,\lambda}$$
 pixel time channel  

$$\mathbf{u}_{n,t,\lambda} \sim \mathcal{N}(\mathbf{0}, \Phi(\mathbf{C}_n^{\text{spat}}, \mathbf{C}_n^{\text{spec}}))$$

$$\Omega = \{m, \kappa, \mathbf{C}_n^{\text{spat}}, \mathbf{C}_n^{\text{spec}}\}$$
 → covariances regularized by shrinkage:  

$$\hat{\mathbf{C}}_n = (1 - \hat{\rho}_n) \hat{\mathbf{C}}_n^{\text{unbiased}} + \hat{\rho}_n \hat{\mathbf{C}}_n^{\text{diagonal}}$$
 bias/variance tradeoff shrinkage factor unbiased but large variance low variance but biased  
**goals** combining this statistical modeling...  
 ...with a reconstruction framework → to improve circumstellar disk reconstruction see Part 2.  
 ...with a learning framework → to improve exoplanet detection sensitivity see Part 3.

### 2. Circumstellar disk reconstruction

**Image formation model:**  

$$\mathbf{r} = \mathbf{A}\mathbf{x} + \mathbf{f}$$
 A(S)DI stack direct model sought object nuisance component  

$$\mathbf{A} := \text{zoom} \circ \text{crop} \circ \text{convolution} \circ \text{attenuation} \circ \text{rotation}$$
**Inverse problem:**  

$$\hat{\mathbf{x}} = \arg \min_{\mathbf{x} > 0} \mathcal{D}(\mathbf{r}, \mathbf{A}\mathbf{x}, \Omega) + \mathcal{R}(\mathbf{x}, \mu)$$
 data fidelity regularization  
 → data fidelity with joint estimation  $\mathbf{x}$  and  $\Omega$ :  

$$\mathcal{D}(\mathbf{r}, \mathbf{A}\mathbf{x}, \Omega) = \frac{1}{2} \sum_{n \in \mathbb{P}} \sum_t \log \det \hat{\kappa}_{n,t}^2(\mathbf{x}) \hat{\mathbf{C}}_n(\mathbf{x}) + \frac{1}{2} \sum_{n \in \mathbb{P}} \text{tr} \left[ \hat{\mathbf{C}}_n^{-1}(\mathbf{x}) \left( \hat{\mathbf{W}}_n \odot \sum_t \hat{\kappa}_{n,t}^{-2}(\mathbf{x}) \hat{\mathbf{v}}_{n,t}(\mathbf{x}) \hat{\mathbf{v}}_{n,t}(\mathbf{x})^t \right) \right]$$

$$\hat{\mathbf{v}}_{n,t}(\mathbf{x}) = \mathbf{r}_{n,t} - \hat{\mathbf{m}}_n(\mathbf{x}) - [\mathbf{A}\mathbf{x}]_{n,t} \text{ (residuals)}$$

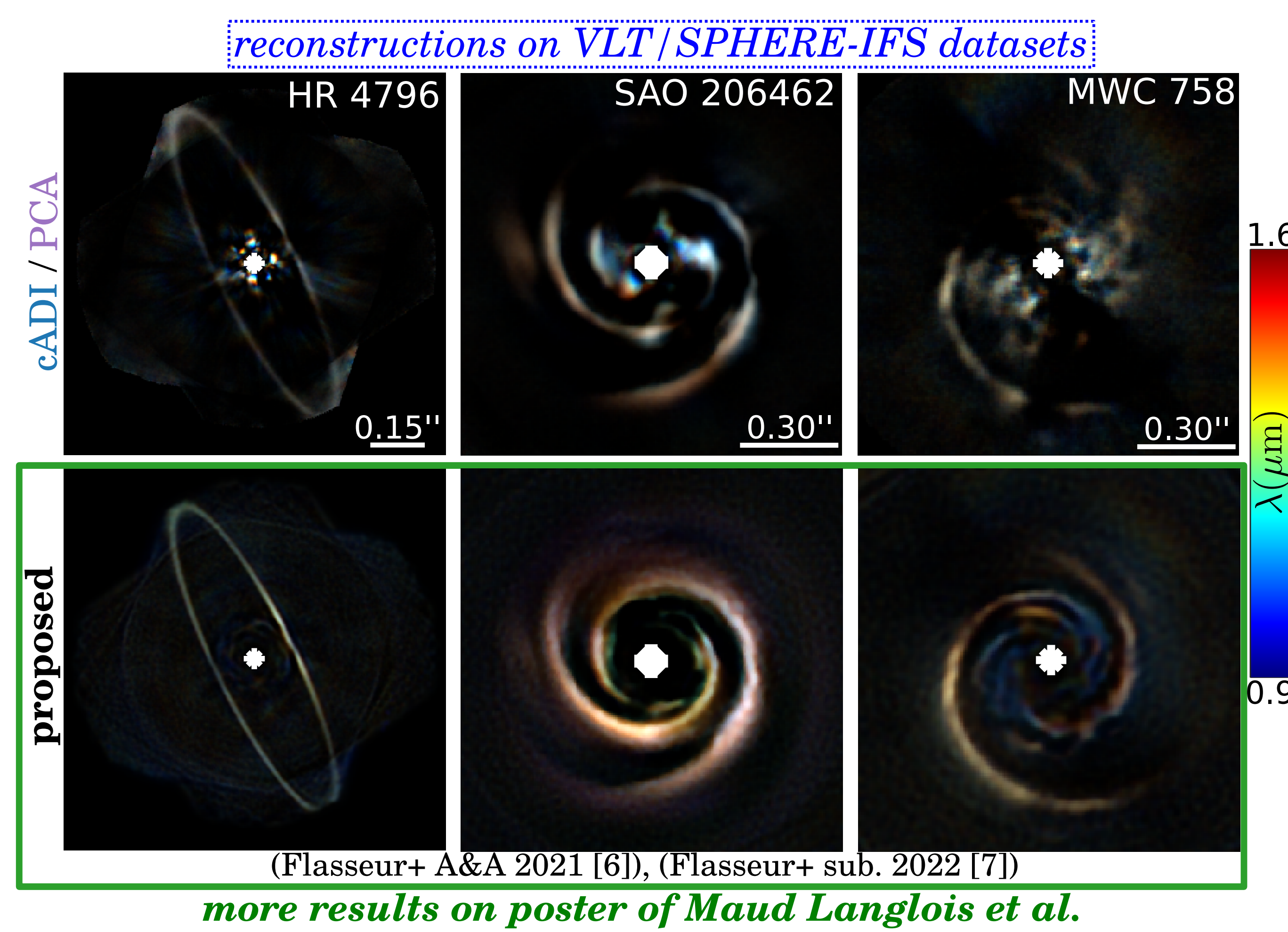
$$\hat{\mathbf{W}}_n = (1 - \hat{\rho}_n) + \text{diag}(\hat{\rho}_n) \text{ (shrinkage)}$$

**proposed method**  
 → regularization with unsupervised setting of  $\mu$ :  

$$\mathcal{R}(\mathbf{x}, \mu) = \mu_{\text{t1}} \sum_{n=1}^N |x_n| + \mu_{\text{smooth}} \sum_{n=1}^N \sqrt{\|\Delta_n \mathbf{x}\|_2^2 + \epsilon^2}$$
 sparsity edge-preserving  
 optimal  $\mu$  minimizes SURE (MSE estimator [4]) adapted to account for  $\Omega$ :  

$$\text{SURE}(\mu) = \sum_{n \in \mathbb{P}} \sum_t \|r_{n,t} - \hat{\mathbf{m}}_n - [\mathbf{A}\hat{\mathbf{x}}_\mu(r)]_{n,t}\|_{\hat{\kappa}_{n,t}^{-2} \hat{\mathbf{C}}_n^{-1}}^2 + 2 \text{tr}(\mathbf{A}\mathbf{J}_{\hat{\mathbf{x}}_\mu(r)}) - N$$
 but no closed-form expression for Jacobian  $\mathbf{J}$   
 ⇒ perturbation approach [5]:  

$$\text{tr}(\mathbf{A}\mathbf{J}_{\hat{\mathbf{x}}_\mu(r)}) \approx \xi^{-1} \mathbf{b}^t \mathbf{A} [\hat{\mathbf{x}}_\mu(r + \xi \mathbf{b}) - \hat{\mathbf{x}}_\mu(r)]$$



### 3. Exoplanet detection

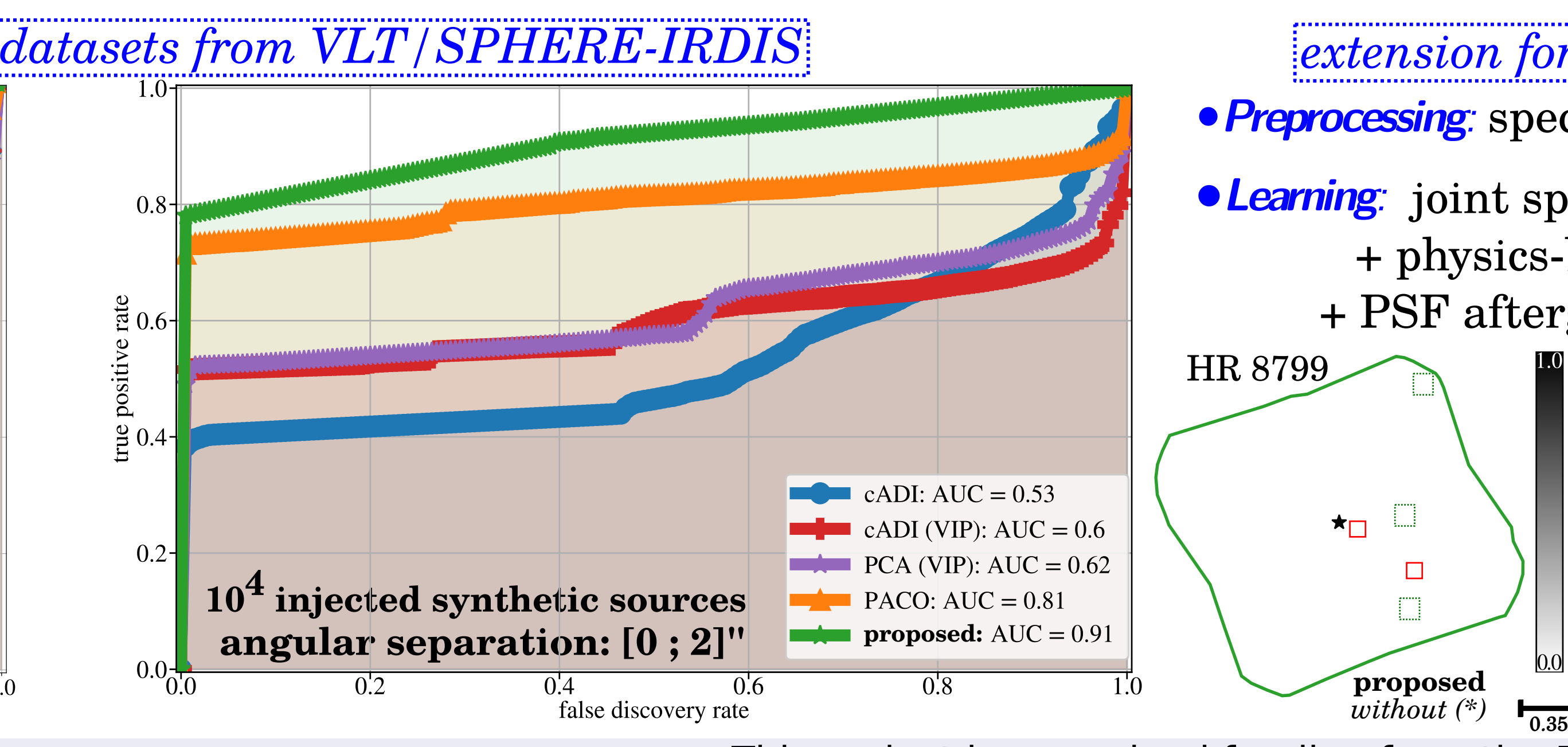
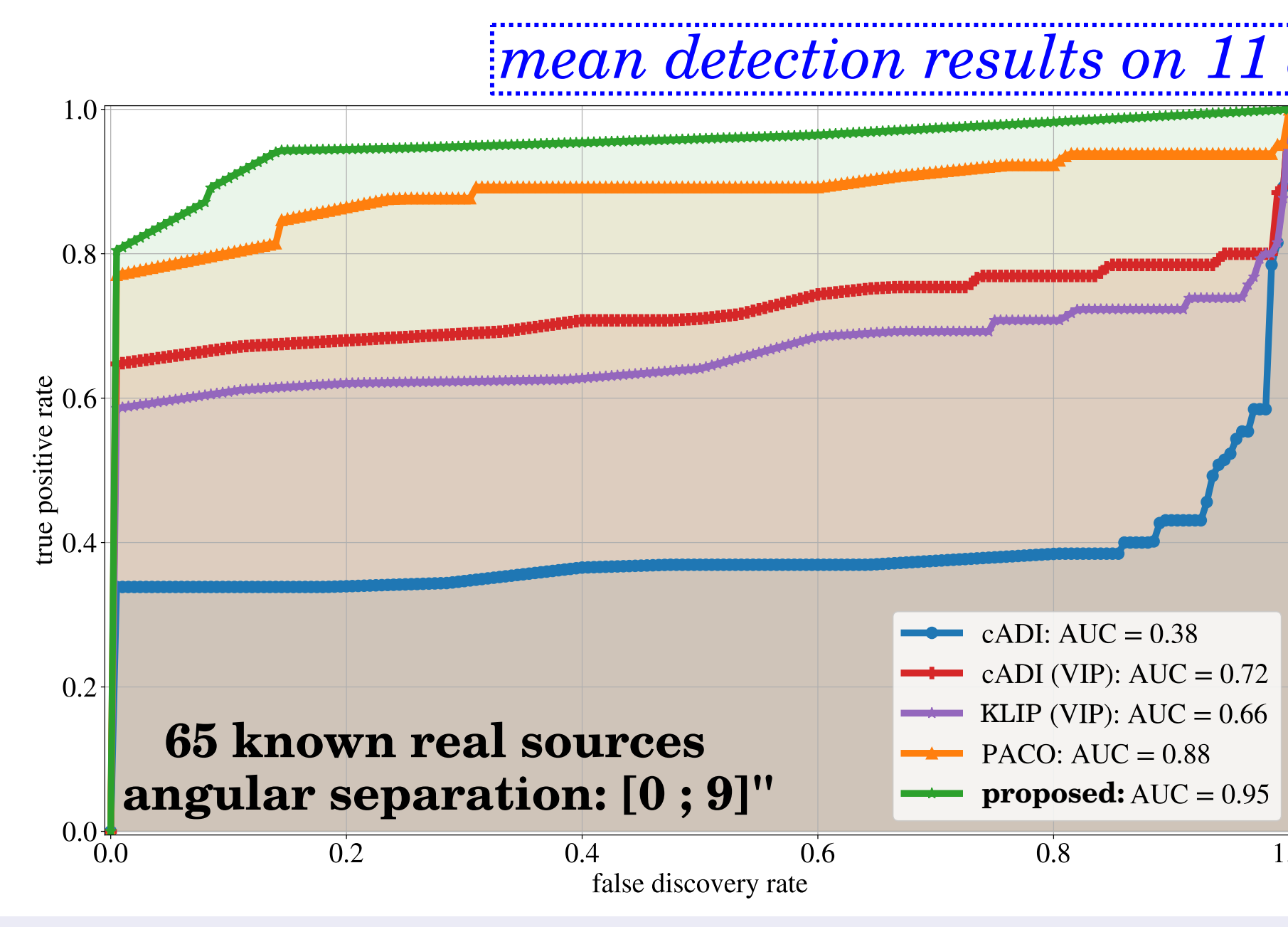
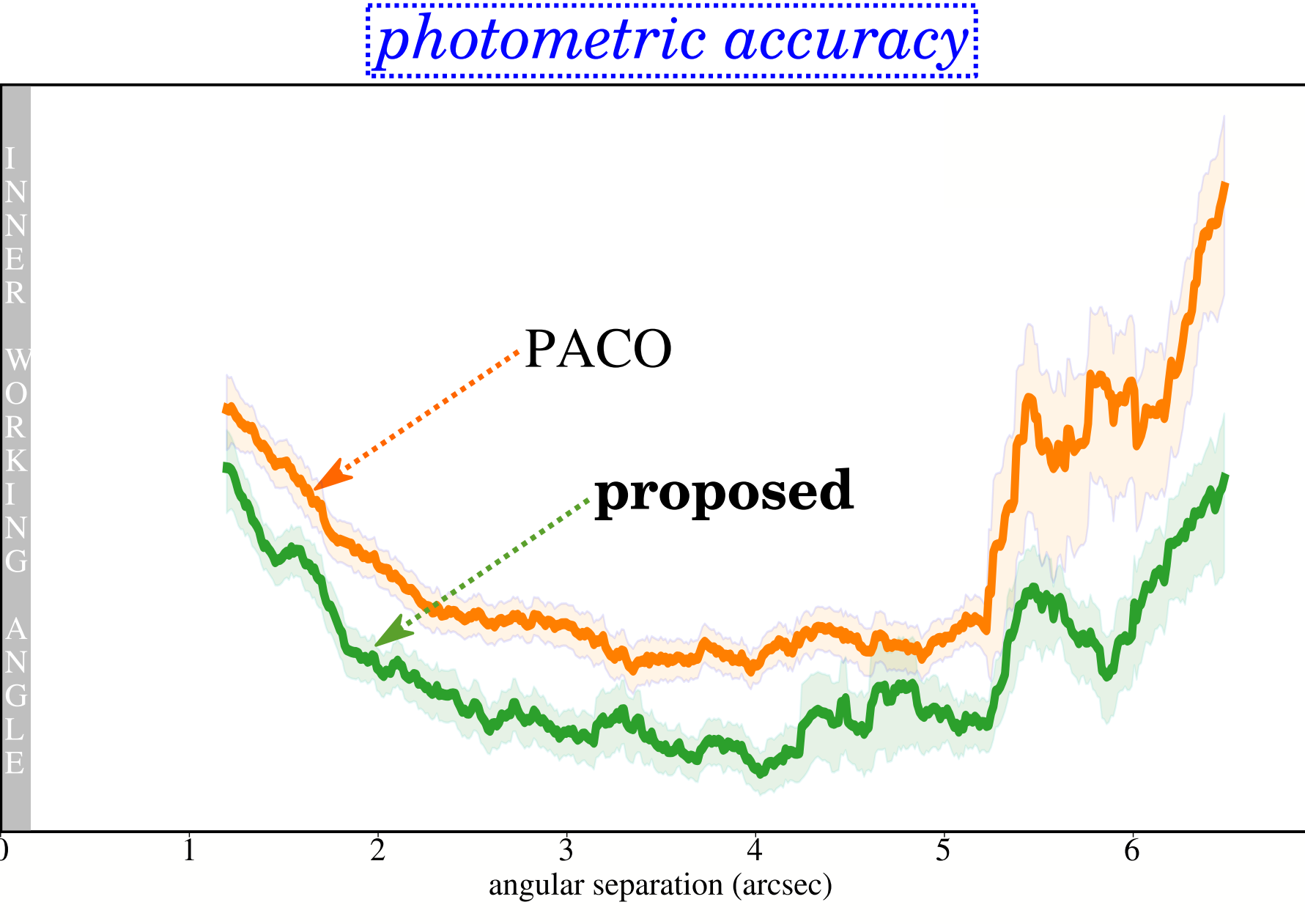
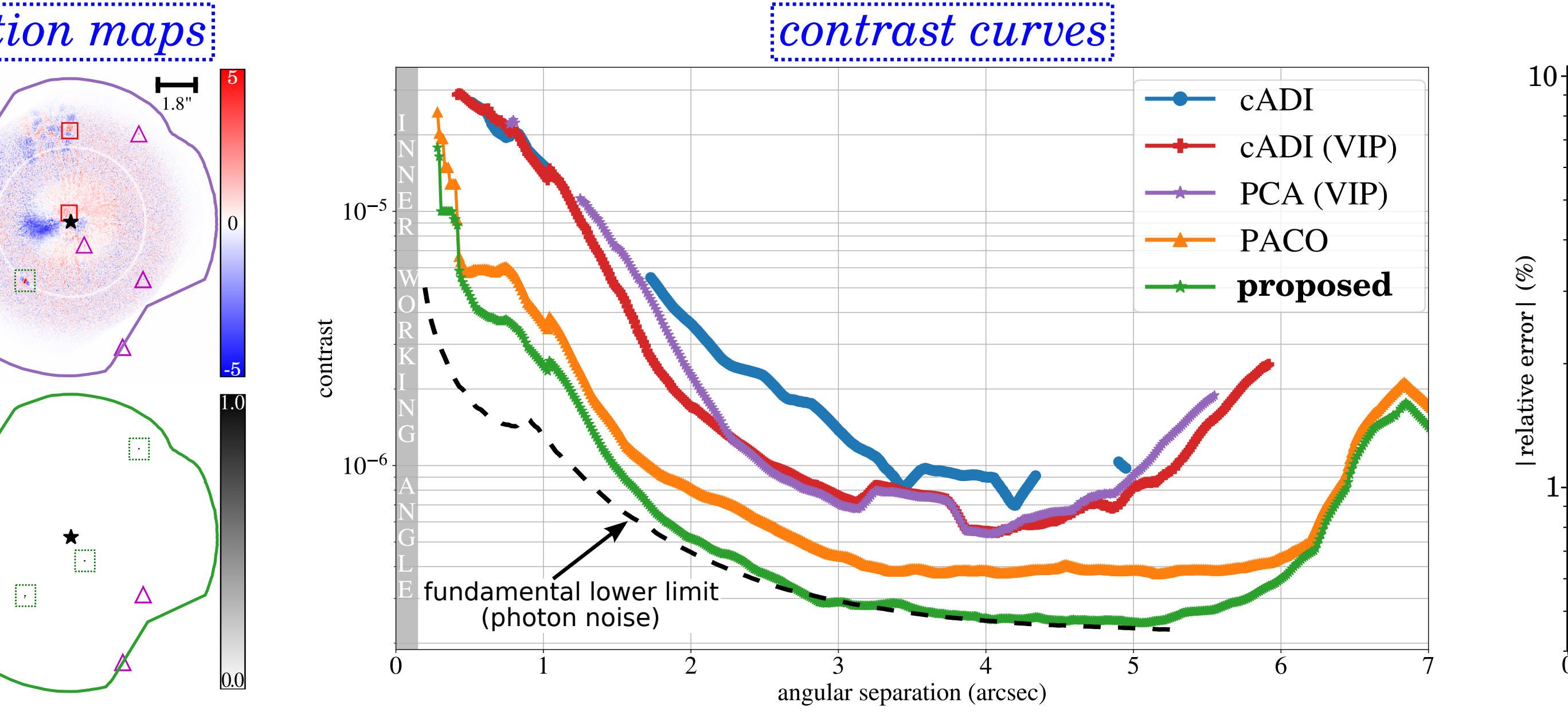
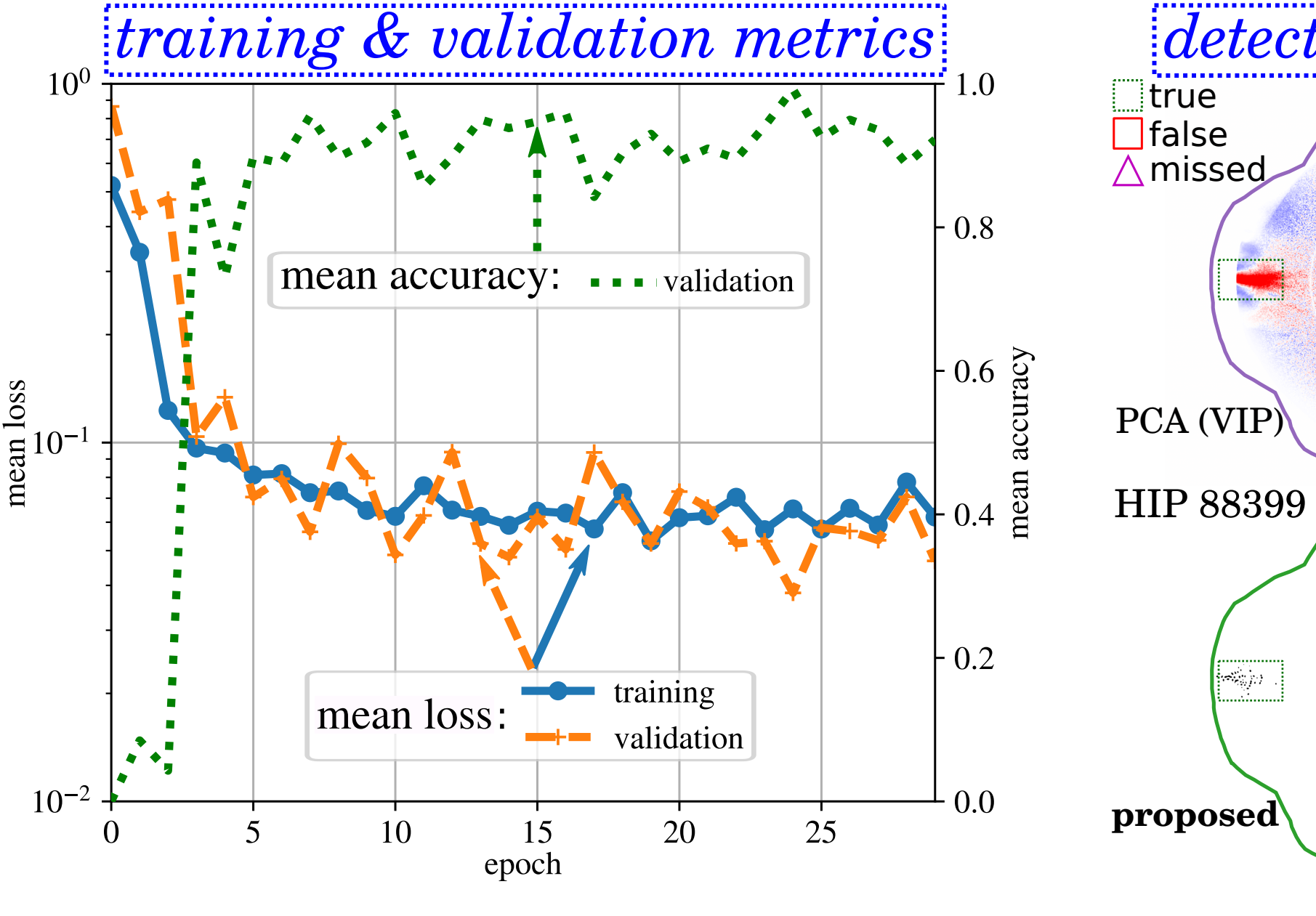
**Preprocessing:** centering and local whitening with statistical model of the nuisance  
 → to improve SNR and stationarity  
 contains almost noise  
 parameter-free  
 local adaptivity

**proposed method**  
 • **Learning:** supervised training with simulated exoplanets  
 → to correct small discrepancies statistical model/observations  
**samples:** preprocessed images + shuffling + injected fake exoplanets  
 data augmentation to deal with lack of groundtruth  
**groundtruths:** location + intensity  

$$k = 1:K$$

**semantic segmentation**  
 CNN (full frames)  
 output: detection map  
 Dice score (overlap measure)  
 validation metric: F1R score (tradeoff precision/recall)  
 architecture: U-Net (backbone Res-Net18) trained from scratch

**regression**  
 CNN (patches)  
 output: estimated intensity  
 MSE  
 architecture: VGG-like



**extension for ASDI data**  
 • **Preprocessing:** spectral correlations  
 • **Learning:** joint spectral model + physics-based spectra<sup>(\*)</sup> + PSF afterglow simulation<sup>(\*)</sup>

**on-going & future works**  
 control the uncertainties (statistically interpretable detection confidence)  
 include physics-based priors (hybrid approaches)  
 consider other tasks (reconstruction of disks)

HR 8799  
 proposed without (\*)  
 proposed with (\*)

erc  
**COBREX**  
 European Research Council